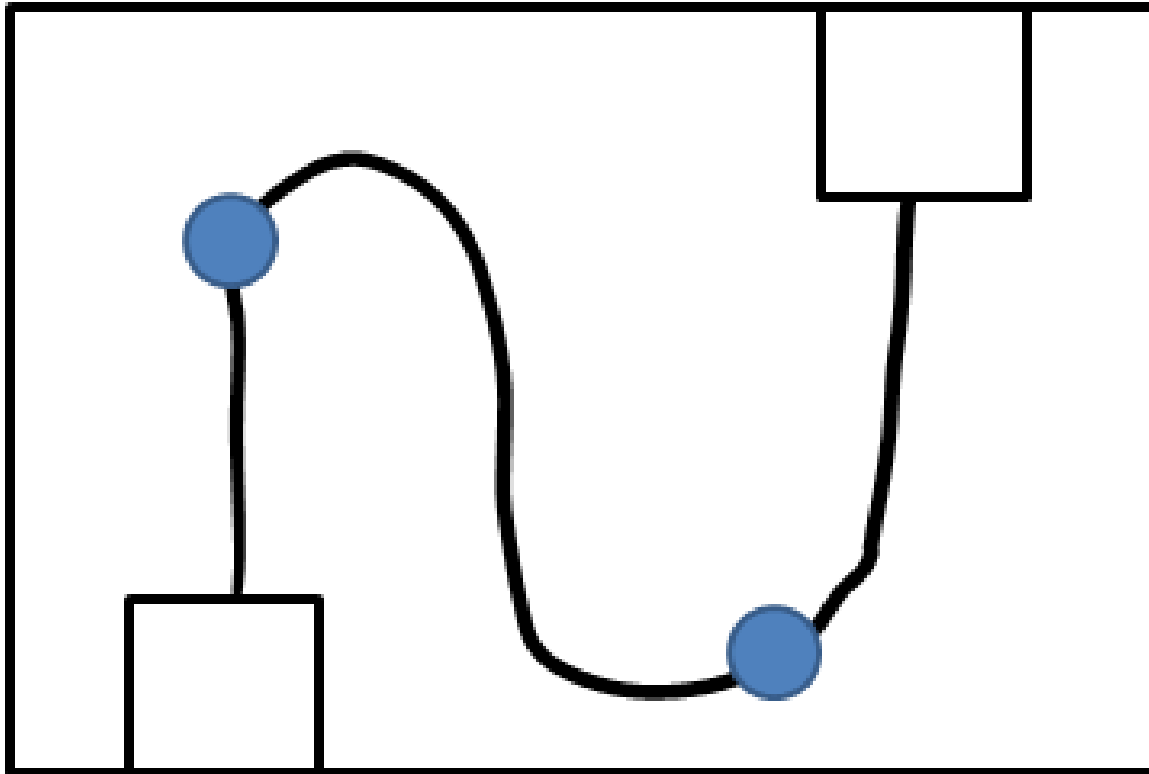


Line follow and stop



Program the robot to track the line and stop when the sonar sensor detects an obstacle. When the obstacle is moved, the robot should continue down the line.

Line Follow Sample Program

